Modulus Mesh Communications modules have built-in 1/4W 900MHz Meshing Radios compatible with Scadaflex II controllers, and Scadaflex II battery powered and distributed Remote I/O modules. Meshing radios automatically form self-healing repeater links to get messages through the network, even when an intermediate node becomes unavailable. They also support wired communications with Modbus, DF1, Ethernet IP, SDX, MQTT, and SDI-12.

The Mesh Communications modules have built-in analog and digital I/O for tank level and process monitoring, and pump control applications such as lift stations and booster pumping stations. The base modules have a choice of analog inputs supporting either mA, voltage or resistance/temperature measurement, along with a high-speed discrete input and a FET discrete output. Additional I/O, consisting of 16 discrete inputs, 5 relay outputs, a couple more 20mA analog inputs, and 4 analog outputs, is brought out on an external field wiring panel.

Modulus Mesh Communications modules have two serial ports (bus port plus one general purpose port). The bus port may also be used for general purpose RS-485 communications when not bussed with other I/O modules.

**STANDALONE OPERATION**
Modulus Mesh Communications modules can serve as standalone devices with SCADA communications, local and web human machine interfaces (HMI), historical trending and data logging, alarming, reporting, and programmable logic.

**COMMUNICATIONS**
Modulus Mesh Communications modules have a built-in 1/4W 900MHz license-free spread spectrum radios that can form a self-healing high-reliability wireless network between controllers and remote I/O. They also have an Ethernet port and two serial ports to communicate with Modbus devices and Allen Bradley PLCs. They can serve as communications concentrators or master controllers, as well as providing web and data access to any other Modulus modules on the high-speed bus. They support Ethernet to Serial bridging, and routing through Ethernet ports in other Modulus modules on the bus.

**GRAPHICAL, MOBILE, AND LOCAL HMI**
Configurable graphical and mobile device web interfaces, including the tools and libraries to build custom screens, are built in. The front panel display can also be customized to show live process values and states, and make setting changes.

**HISTORICAL TRENDING AND EVENT LOGGING**
Modulus Mesh Communications modules have an internal flash disk, as well as a micro SD memory card slot to record over 100 years of data! Use built-in web tools to retrieve and display historical trend and event data and extract it as spreadsheet files.

**REPORTING**
Reports with custom graphics and logos can be created in minutes, showing live values, totals, trend/event data, alarm summaries, etc. They can be called up on demand, or sent out automatically.

**ALARMING**
A Modulus Mesh Communications module can manage alarm conditions on any of it’s local inputs and other Modulus I/O on the bus, as well as external devices via communications. Alarms conditions can be displayed locally and annunciated by text message and e-mail alerts. Alarms can be acknowledged by text message or e-mail, discrete input, or local HMI button. The module maintains a journal spreadsheet file of when alarms occurred, when they were acknowledged, by whom, and when the alarm conditions clear.

**PROGRAMMABLE LOGIC**
Modulus Mesh Communications modules support programmable logic written in ladder logic, function block and text languages; all with 32-bit integer and floating point math. Programmable logic can supplement the built-in functions of the module.

**PID & PUMP CONTROL**
Modulus Mesh Communications modules have a quad PID controller and a triplex pump controller (float or level control) with error detection and alarming. The Mesh Communications Module is an ideal solution for SCADA operation of wells, lift stations, and booster pump stations.

**REDUNDANCY**
Modulus Mesh Communications modules support redundancy for enhanced reliability. If a module goes off-line, a designated backup can take over automatically.
## FIELD I/O

**Discrete Inputs:** 1
- **Input Range:** Contact closure/open collector driver to ground, or 0 to 30Vdc (ON=0.5mA, OFF > 2.5V)
- **Input Current:** Approximately 0.5mA (internal current source)
- **Filtering:** Individually configurable: 5Hz, 10Hz, 20Hz, 50Hz, 100Hz, 500Hz, 1KHz, 2KHz, 5KHz, 10KHz+
- **Optically Isolated, bipolar (AC/DC, not polarity sensitive)**
- **Input Range:** 0 to 30V (OFF < 6V, ON>9V)
- **Input Current:** 1.2mA @ 12V, 3mA @ 24V
- **Filtering:** Individually configurable: 20Hz or 100Hz

**Discrete Outputs:** 1
- **Output Rating:** 30Vdc, 2A maximum, current limited to approximately 2.25A.
- **Relays:** Form A (normally open), individually isolated (no shared common)
- **Output Rating:** 240/277 Vac, 30Vdc, 3A maximum per output (resistive load).

**Analog Inputs:** 2
- **Input Range:**
  - [8X-5181]: 20mA (Minimum input for full accuracy is 0.5mA)
  - [8X-5281]: 5V, +/-5V, 10V, +/-10V, 30V
  - [8X-5381]: 50K ohms, temperature using 2.2K, 10K (type II, III and w/11.2K shunt) thermistors
- **16-bit, Delta Sigma, individually software configurable ranges**
- **Analog Outputs:** 4
- **Output Ranges:**
  - 0-20mA, 4-20mA

## COMMUNICATIONS

**Ethernet:** 1
- **10/100mb/s (10/100 Base-T)**
- **SCADA Protocols:** Modbus TCP & UDP (master/slave), Ethernet IP (master/slave PLC5 & SLC5/05 emulation), SDX (AES-128 Encryption), MQTT, Ethernet to Serial bridging
- **Internet Protocols:** HTTP (server), FTP (server & client), E-mail (SMTP and POP3), ICMP (ping; server & client), NTP (client), DHCP (server & client), DNS, DDNS

**Wireless:** 1
- **900MHz 1/4W (24dBm) Frequency Hopping Spread Spectrum meshing radio, -101 dBm sensitivity @ 200kbps, up to 64 remote nodes**

**Serial:** 1
- **RS-232, RS-485, RS-422, SDI-12** (for general purpose communications)
- **RS-485 Bus port** (this port is available for general purpose communications if not used for high-speed bus communications with other modules)
- **Baud Rates (all ports):** 115K, 38.4K, 19.2K, 9600, 4800, 2400, 1200 baud.
- **Protocols:** Modbus RTU (master/slave), DF1 (slave), SDX (AES-128 Encryption), SDI-12 (general purpose port only)**

**HMIs**
- **Local:** 128x32 graphical, wide temperature range yellow OLED and single pushbutton
- **Graphical:** Web based, graphic library included. Compatible with most browsers, including Internet Explorer, Firefox, Chrome, Safari, Android
- **Mobile:** Web based, text only, up to 50 registers. Compatible with most browsers, including Internet Explorer, Firefox, Chrome, Safari, Android

## PROGRAMMING
- **Languages:** Ladder Logic, Function Block, Text—built-in web based graphical and text editor and debugger
- **Capacity:** 64KB logic, 2MB source code, 32-bit integer and floating point math

## STORAGE
- **Registers:** 504 Numeric registers, 504 Boolean registers
- **Internal Flash disk:** 32MB
- **Removable disk:** Micro SD Card (up to 256GB, supplied by customer)

## CLOCK
- **Real Time Clock:** Temperature compensated with lithium battery backup power
- **Stability:** +/- 3ppm from –30°C to 70°C

## GENERAL
- **Input Power:** 10Vdc to 30Vdc

## Power Consumption
- **(not including analog output current)**
  - **Not using Ethernet:** 68mA @ 12Vdc / 40mA @ 24Vdc (Ethernet power saver enabled)
  - **Using Ethernet:** 108mA @ 12Vdc / 60mA @ 24Vdc
  - **Radio Transmitting:** Add 100mA @ 12Vdc 50mA @ 24Vdc in short transmit bursts
  - **Add current per on relay:** 10mA @ 12Vdc / 5mA @ 24Vdc

## Field Wiring Termination:
- **[81-5x8x] screw terminal blocks**
- **[82-5x8x] lever terminal blocks**, 3.5mm, 22 to 14GA wires

## Specifications subject to change without notice. Consult factory to ensure that you are working with current information.
Mesh Spread Spectrum radio systems use antennas mounted external to the controller. The type of antenna used depends on both the distance to be covered and the terrain between any two sites that are to be linked together. The selection of antennas, mounting height above grade, cable types, etc. should be determined by use of a radio path study to ensure reliable communications. There are three types of antennas typically used:

- **“Salt Shaker” style Omni-directional for moderate distances**
- **6dB Omni-directional for best performance at a Master or repeater site**
- **6dB Yagi directional for best noise rejection and signal focus at remote sites**

### Yagi Antenna System

A “Salt Shaker” style antenna is the lowest cost, and easiest type to deploy in the field. It can be mounted on the top of the equipment panel and works well for moderate communications distance. Since it is omni-directional, there is no aiming or alignment required in the field. The antenna part number is 98-3103, and connects to the communications module with a short internal antenna cable (part number 98-6536).

### Omni Antenna System

Using elevated higher gain antennas can significantly improve the performance and reliable operating distance of a radio system. Since elevating the antennas will also increase the installation and maintenance cost of the system, you should always have a radio path study done to select the antenna components and mounting arrangements. Omni-directional antennas do not need to be aimed while Yagi directional antennas will provide better off-axis noise rejection. For either type of antenna system, a lightning arrestor is generally recommended since by being elevated, the antennas become a better “target” for a lightning strike. Use a dedicated grounding rod and bonding as shown for the lightning arrestor.

### Antenna Components for Maximum Communications Distances

Using elevated higher gain antennas can significantly improve the performance and reliable operating distance of a radio system. Since elevating the antennas will also increase the installation and maintenance cost of the system, you should always have a radio path study done to select the antenna components and mounting arrangements. Omni-directional antennas do not need to be aimed while Yagi directional antennas will provide better off-axis noise rejection. For either type of antenna system, a lightning arrestor is generally recommended since by being elevated, the antennas become a better “target” for a lightning strike. Use a dedicated grounding rod and bonding as shown for the lightning arrestor.

### Antenna System BOM:

- **98-6536** 36” Internal Antenna Cable
- **98-8011** Lightning Arrester
- **98-42xx** Low-loss Antenna Cable (xx= length in feet)
- **98-2106** Spread Spectrum Yagi Directional Antenna
- **98-3106** Spread Spectrum 6dB Omni-directional Antenna
- **98-9002** Weatherproofing Kit (for external antenna connections)
Refer to the installation manual for additional installation details and precautions.

**Discrete Input DI1, Discrete Output DO1 & Analog Inputs — TB1**

The field wiring may be connected directly to the TB1 terminal block, or through a field Wiring Panel as shown in the diagrams below. All discrete inputs/outputs and analog inputs are referenced to the ground terminal (5). This terminal is connected internally to the power supply ground.

The Discrete Input accepts a contact closure or open-collector ("NPN" style) input signal. An external pull-up resistor is not required.

The Discrete Output sources current by switching the module input power to the output terminal.

The 8x-5181 model has analog Inputs that accept 20mA current signals. Loop powered (Figure A) and self-powered (Figure C) devices are supported. In power conserving applications, the analog sensors may be powered from the Discrete Output (Figure B), configured to switch power to the sensors only when needed to take an analog reading (with configurable "warmup" time).

The 8x-5281 model has analog Inputs that support voltage sensors (+/-5v, +/-10v and 30v) while the 8x-5381 model supports resistance sensors including thermistor type temperature sensors. The wiring for these sensors is shown in Figure D below.

Note that for loop powered devices, model 82-01xx Field Wiring Panels should be used. For self-powered devices, either model 82-00xx or 82-01xx Field Wiring Panels may be used.

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8x-5181 (20mA Analog Inputs)

**Figure A**

20mA Loop Powered Sensors

External Loop Supply

**Figure B**

Sensor Power from Discrete Output

**Figure C**

Self-powered 20mA Sensors

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8x-5281 (Voltage) and 8x-5381 (Resistance/Temperature) Analog Inputs

**Figure D**

Voltage and Resistance Sensor Wiring

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Optional Field Wiring Panel
Extended I/O Field Wiring Panel 8x-5x81

Discrete Outputs Wiring

Discrete Inputs Wiring

Analog Inputs Wiring
- Loop Powered Devices
- Self Powered Devices

Analog Outputs Wiring

Refer to the installation manual for additional installation details and precautions.

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